

Dieses Wahlpflichtmodul ist ein Angebot der:

Fachhochschule Dortmund

Master Embedded Systems for Mechatronics

University of Applied Sciences and Arts

Signals and Systems for Automated Driving

masteresm@fh-dortmund.de +49 (0)231 9112-7991

Prof. Dr. Andreas Becker andreas.becker@fh-dortmund.de





Fachhochschule Dortmund University of Applied Sciences and Arts







Cod	e Number	Workload	Credits	Semeste	r Frequency	Duration		
	10404	180 h	6		annually	1 Semester		
1	Cou	irse Title	Conta	ct hours	Self-Study	Planned Group		
		Systems for	4 SW	'S / 60 h	120 h	Size		
	Automated	Driving				25 students		
)		scription						
2	Course Description Automated driving requires the use of a multitude of sensors, controllers and actuators installed							
	on the vehicle. Additionally, vehicle to vehicle and vehicle to infrastructure communication vehicles are served. This course gives an overview about technologies used for automated driving starts with an overview about current R&D trends and then covers several sensor technologie with a special focus upon radar. Students will learn basic principles of stochastic sign processing and its application to tracking and mapping. Motion models and vehicle cont technologies will be discussed to gain further insight into requirements for sensors a algorithms. Additional focus of this course is on architectures and infrastructures for automate driving. This includes bus interfaces and SW architectures as well as the basic principles systems engineering. ISO 26262 as well as legal frameworks and their application to automate driving will be discussed. In addition to the lecture, exercises and small projects give additional focus is introduced in this course.							
	Course Structure							
	2. Ser 3. Sign 4. Actu 5. Sys 6. Sys 7. ISC	chnology overvi- nsors nal processing uators & Vehicl tem Architectur tem Engineerir 26262 gal frameworks	e Control res					
	Parameters							
	Cou Cap Cou Cou Skil Ass	Is trained in this essment of the	every year - ents prerequisite s course: the course: Oral	summer sen es: higher ma oretical, prac	nester thematics, programmi trical and methodologic in) at the end of the cou	al skills		
	 work as homework (50%) Teaching staff: Prof. Dr. Andreas Becker 							
5	Learning o	Learning outcomes						
	Kno Kno	-	I processing ation algorith	algorithms for ms				

	 5.3 Competence – attitude Understands the challenges in the development of automated driving and can discuss with experts from different domains Can lead development of subsystems for automated driving Can lead system level tests for automated driving 				
6	Teaching and training methods				
	 Lectures, Labs (with Matlab/Simulink) Access to tools and tool tutorials Access to recent research papers Company visit 				
6	Course mapping				
_	Requires: MOD1-01 - Mathematics for Signals & Controls Connects to: MOD1-04 - Requirements Engineering MOD2-01 - Mechatronic Systems Engineering MOD-E10 - Automotive Systems MOD-E06 - Computer Vision				
7	References				
	Winner et al., Handbook of Driver Assistance Systems, Springer reference, 2016				
	Pebbles, Radar Principles, John Wiley & Sons, 1998 Bar-Shalom et al., Estimation with Applications to Tracking and Navigation, John Wiley & Sons, 2001				
	Maurer et al., Autmotive Systems Engineering, Springer 2013				