

Dieses Wahlpflichtmodul ist ein Angebot der:

Fachhochschule Dortmund

Master Embedded Systems for Mechatronics

University of Applied Sciences and Arts

Signals & Control Systems 1

masteresm@fh-dortmund.de +49 (0)231 9112-7991

Prof. Dr. Andreas Becker andreas.becker@fh-dortmund.de

Hochschule Bochum Bochum University of Applied Sciences



Fachhochschule Dortmund University of Applied Sciences and Arts







Code Number Workload		Credits Seme		r Frequency	Duration		
	10240/41	180 h	6	Sem. 2	annually	1 Semester	
1	C	ourse Title	Conta	ct hours	Self-Study	Planned Group	
	Signals & 1	Control Systems	4 SW	'S / 60 h	120 h	Size 25 students	
2	Course D	escription					
	 Cyber-physical systems (CPS) interact with the physical world by making use of sensors and actuators. Their main source of information is a variety of signals. The analysis, processing and understanding of signals and the inherent information is a central topic for the development of mechatronic systems. This module delivers the theoretical foundations for the understanding of signal processing and control engineering problems and algorithms. The description of sensors and actuators by linear time-invariant systems is a powerful tool for the description of the dynamic behavior of mechatronic systems. The corresponding concepts are dealt with in the first block of this course. Control systems are the connection between the mechanical/physical world and the control 						
	 task performed by the embedded system. The goal of this module is to enable students to interact with control system experts and to integrate their results into embedded and mechatronic systems by learning the basic principles of feedback and control engineering. Embedded signal processing and control systems are based upon time-discrete calculations. 						
	Thus a major focus of this course is to deal with time discrete signals and systems and the transformation from continuous time to discrete time.						
	Filters play a major role in the processing of data and they are widely used in signal processing and control engineering tasks. The analysis starts with continuous time filters and then introduces canonical structures for FIR and IIR filters.						
	An additional goal is to teach the use of advanced tools for signal processing and control system design.						
3	Course Structure						
	2. S 3. Li 4. S 5. S 6. C 7. A	near time-invarian tate variable mod near feedback an ampling theorem tructures for discr ontinuous time ar pplications of the ignal processing a	els d control sys and discrete ete time sys id discrete ti above	Fourier-trans tems me filters (FII			
4	Parameters						
	 Course characteristics: compulsory Course frequency: every year - winter semester 						
	• C	apacity: 25 stude	nts				

Fachhochschule Dortmund University of Applied Sciences and Arts

	Course admittance prerequisites: higher mathematics					
	 Skills trained in this course: theoretical and methodological skills 					
	Assessment of the course: Written Exam (90 min) at the end of the course (100%)					
	Teaching staff: Prof. Dr. Andreas Becker, (Prof. Dr. Jörg Thiem)					
5	Learning outcomes					
	5.1 Knowledge					
	 Knows relevant theoretical foundations of signal processing and control theory 					
	Knows mathematical background of linear feedback controllers					
	Is aware of critical limitations of discrete time signals and the impact of sampling					
	Knows basic analogue and digital filters					
	5.2 Skills					
	Can analyze systems and signals					
	Can model linear feedback controllers for mechatronic systems					
	 Can apply and design digital filters 					
	5.3 Competence - attitude					
	Can discuss control system design for mechatronic systems with experts					
	Can lead cross domain design of control systems					
	Understands control system experts and translates between different domains					
6	Teaching and training methods					
	Lectures & Exercises, Matlab/Simulink labs					
	e-learning modules on mathematics and control theory, tool tutorials					
7	Course mapping					
	Input for					
	Input for:					
	MOD-E04 - Signals and Systems for Automated Driving					
	MOD-E06 – Computer Vision					
	MOD-E07 – Signals & Control Systems 2					
	Requires:					
	MOD1-01 - Mathematics for Signals & Controls					
8	References					
	D. Dishen, D. Darfi Madam Control Systems, Descrete Education, 2010					
	R. Bishop, R. Dorf: Modern Control Systems, Pearson Education, 2010					
	Oppenheim, Willsky, Nawab, Signals and Systems, Pearson Education, 2013					
1						