

Dieses Wahlpflichtmodul ist ein Angebot der:

Fachhochschule Dortmund

Master Embedded Systems for Mechatronics

University of Applied Sciences and Arts

Mathematics for Signals & Controls

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Hochschule Bochum Bochum University of Applied Sciences



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Cod	e Number	Workload	Credits	Semeste	r Frequer	ncy	Duration	
	0110/11 180 h		6	Sem. 1	annual	ly	1 Semester	
1	Course Title		Conta	ct hours	Self-Study	Planne	ed Group Size	
	Mathematic Controls	s for Signals &	4 SW	/S / 60 h	120 h	25	25 students	
2	Course Des	scription						
	engineering different kin amount of p the latter an with several noise or ot introduced.	It starts with a lds of integral to hysical phenom e dealt with in th I states and/or r her sources of	a tailored re ansforms th ena can be nis course. L nultiple inpu uncertainty tave are us	view of real a nat are of ess described by Linear algebra ts and output To be able ed as examp	concepts for sign and complex anal sential use in subs sets of linear differ a plays a prominer is. Usually, sensor to deal with the oles for state of th ses.	ysis. A ma sequent co rential equ nt role in c r signals a ose, proba	ajor focus is or purses. A huge ations and thu ase of systems re corrupted by ability theory is	
3	Course Structure							
	2. Fou 3. Diff 4. Line 5. Pro 6. Intro	al and complex a irier, Laplace ar erential equation ear algebra bability theory oduction into Ma nerical mathem	nd Z transfor ns atlab/Octave					
4	Parameters							
	Course characteristics: compulsory Course frequency: overviveer winter semester							
	 Course frequency: every year - winter semester Capacity: 25 students 							
		urse admittance						
	Ass	essment of the	course: Wri	tten Exam (9	tical and methodo 0 min) at the end c rof. Dr. Thomas F	of the cours		
5	Learning outcomes							
	5.1 Knowled	dge						
	 Knows basic theorems of complex analysis and linear algebra Knows relevant theoretical foundations of signal processing and control engineering Knows the most important concepts of probability theory 							
	5.2 Skills		nalucia and	lin o o r o la o b r	a to describe phys			

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	Can make use of different domains for the description of signals					
	Can apply probabilistic concepts					
	Can make use of tools for numerical mathematics					
	5.3 Competence – attitude					
	Can discuss mathematical prerequisites of mechatronic systems with experts					
	Understands experts for mathematics and translates between different domains					
6	Teaching and training methods					
	Lectures & Exercises					
	Labs with Matlab/Octave					
	E -learning modules on higher mathematics, tool tutorials					
7	Course mapping					
-						
	Input for:					
	Input for: • MOD2-04 – Signals & Control Systems 1					
	Input for: MOD2-04 – Signals & Control Systems 1 MOD-E04 – Signals and Systems for Automated Driving					
	Input for: MOD2-04 – Signals & Control Systems 1 MOD-E04 – Signals and Systems for Automated Driving MOD-E06 – Computer Vision					
	Input for: MOD2-04 – Signals & Control Systems 1 MOD-E04 – Signals and Systems for Automated Driving					
	Input for: MOD2-04 – Signals & Control Systems 1 MOD-E04 – Signals and Systems for Automated Driving MOD-E06 – Computer Vision					
8	Input for: MOD2-04 – Signals & Control Systems 1 MOD-E04 – Signals and Systems for Automated Driving MOD-E06 – Computer Vision					
8	Input for: MOD2-04 – Signals & Control Systems 1 MOD-E04 – Signals and Systems for Automated Driving MOD-E06 – Computer Vision MOD-E07 – Signals & Control Systems 2 References					
8	Input for: MOD2-04 – Signals & Control Systems 1 MOD-E04 – Signals and Systems for Automated Driving MOD-E06 – Computer Vision MOD-E07 – Signals & Control Systems 2					
8	Input for: MOD2-04 – Signals & Control Systems 1 MOD-E04 – Signals and Systems for Automated Driving MOD-E06 – Computer Vision MOD-E07 – Signals & Control Systems 2 References James, Modern Engineering Mathematics, Pearson Education, 2015					